

On the choice of mixing sequences for SNR improvement in Modulated Wideband Converter

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Anastasia Lavrenko, Florian Römer, Giovanni Del Galdo and Reiner S. Thomä
Institute for Information Technology, TU Ilmenau, Germany

Contact Information

■ Prof. Giovanni Del Galdo

Head of DVT Research Group, composed of
Digital Broadcasting Research Laboratory,
Ilmenau University of Technology
Wireless Distribution Systems / Digital Broadcasting Group,
Fraunhofer Institute for Integrated Circuits IIS

office: +49 3677 69-4280
mobile: +49 151 62 91 01 81
e-mail: giovanni.delgaldo@tu-ilmenau.de
giovanni.delgaldo@iis.fraunhofer.de

■ Prof. Reiner S. Thomä

Head of the Electronic Measurement Research Laboratory
(Fachgebiet Elektronische Messtechnik)
Ilmenau University of Technology

office: +49 3677 69-2622
mobile: +49 3677 69-1113
e-mail: reiner.thomae@tu-ilmenau.de

■ M.Sc. Anastasia Lavrenko

PhD Student in the *International Graduate School on Mobile Communications*
Electronic Measurement Research Lab
Ilmenau University of Technology

office: +49 3677 69 1397
e-mail: anastasia.lavrenko@tu-ilmenau.de

■ Dr.-Ing. Florian Römer

Digital Broadcasting Research Laboratory,
Ilmenau University of Technology

office: +49 3677 69 4286
e-mail: florian.roemer@tu-ilmenau.de

Mailing address:
Ilmenau University of Technology,
Helmholzplatz 2
98693 Ilmenau, Germany

Introduction

Noiseless CS formulation

$$\mathbf{d} = \Phi^T \mathbf{s} = \Phi^T \mathbf{A} \mathbf{x} = \mathbf{B} \mathbf{x}$$

$$\mathbf{d} = \Phi^T(\mathbf{s} + \mathbf{w}) + \cancel{\mathbf{e}} = \Phi^T \mathbf{A}(\mathbf{x} + \mathbf{n}) + \cancel{\mathbf{e}}$$

'Signal' noise

Measurement noise

Input SNR

$$\eta_I = \|\mathbf{x}\|_2^2 / E\{\|\mathbf{n}|\lambda\|_2^2\}$$

Output SNR

$$\eta_O = \|\mathbf{Bx}\|_2^2 / E\{\|\mathbf{Bn}\|_2^2\}$$

Recovered SNR

$$\eta_R = \|\mathbf{x}\|_2^2 / E\{\|\hat{\mathbf{x}} - \mathbf{x}\|_2^2\}$$

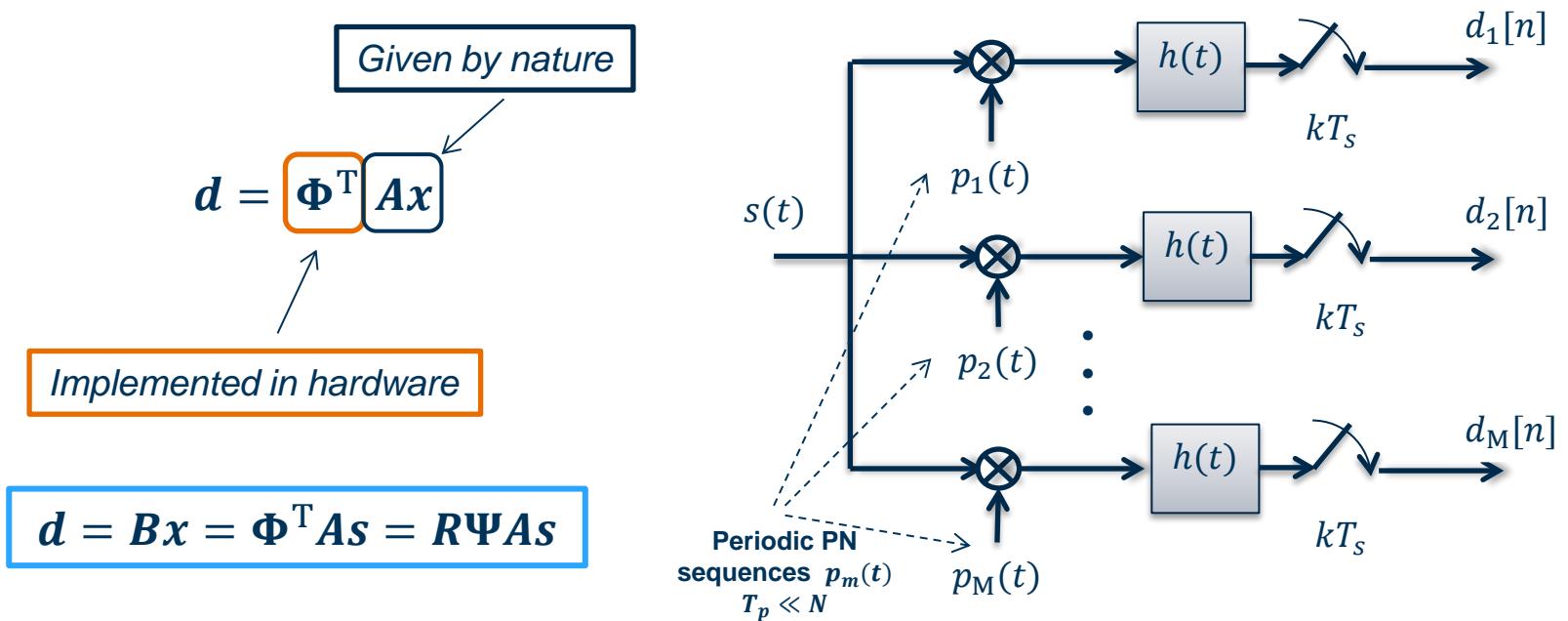
$$\eta_I \quad \Rightarrow \quad \eta_O \quad \Rightarrow \quad \eta_R$$

Outline

- Modulated Wideband Converter
- Noise Folding in the Modulated Wideband Converter
- Frequency-punctured Mixing Sequences
- Some Numerical Results
- SNR - Coherence
- Conclusions

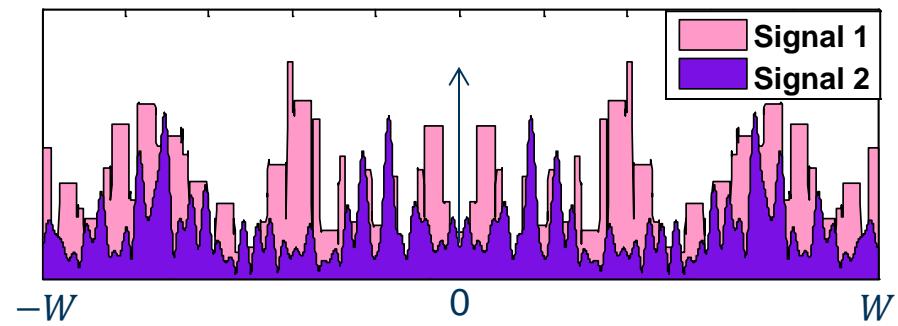
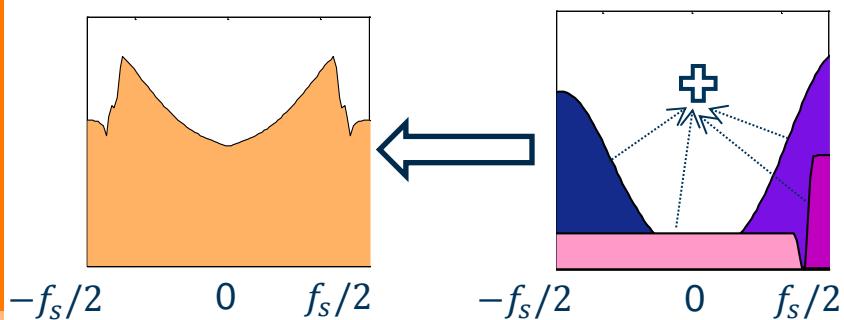
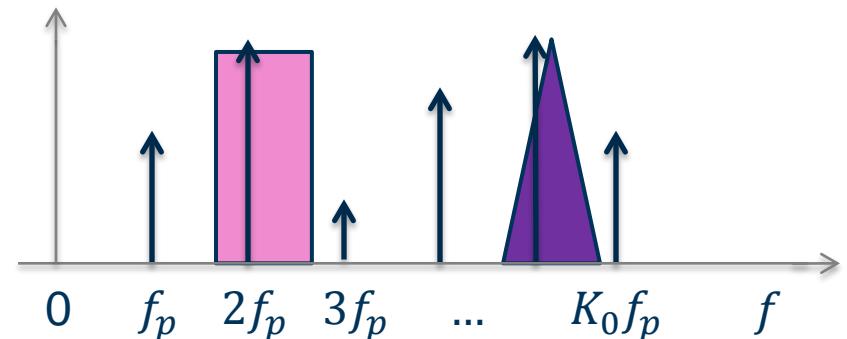
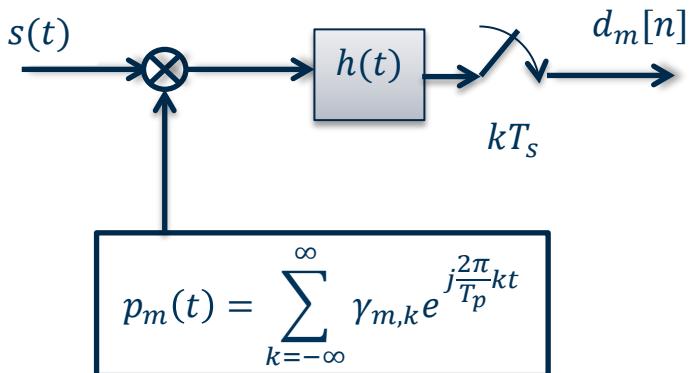
MWC for blind wideband signal acquisition

- Multiband signal
 - Multiple narrowband frequency channels with unknown frequency positions distributed over wide frequency band of interest W .
 - Limited number of active channels L_s so that $\sum_{i=1}^{L_s} B_i \ll W \Rightarrow$ sparse in the frequency domain



*Mishali, Moshe, and Yonina C. Eldar. "From theory to practice: Sub-Nyquist sampling of sparse wideband analog signals." *Selected Topics in Signal Processing, IEEE Journal of* 4.2 , 2010.

MWC in frequency domain analysis



Noise folding in the MWC

Input SNR

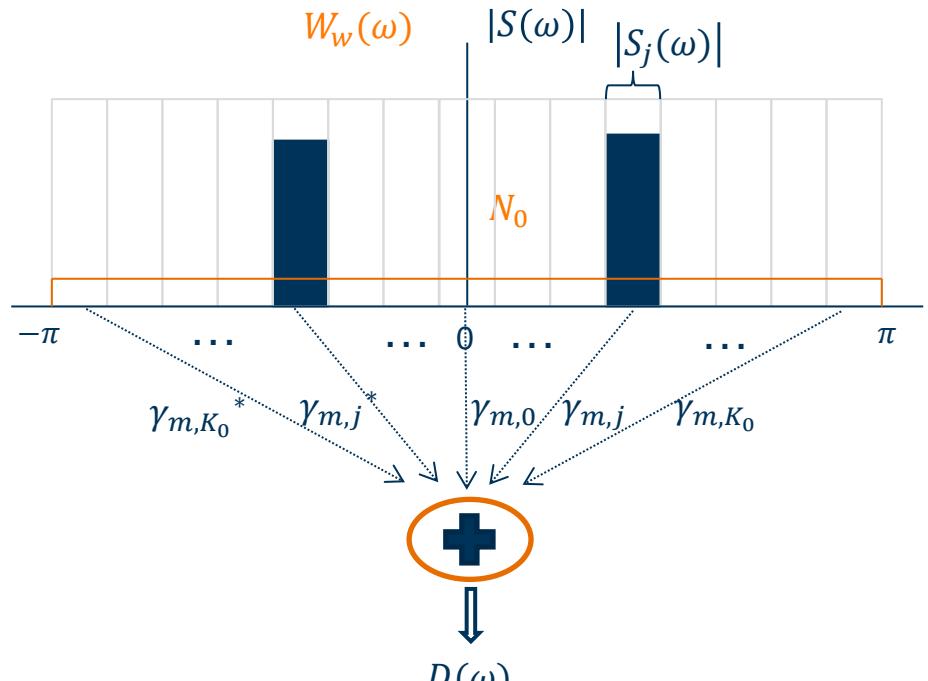
$$\eta_I = \frac{\text{total input signal power}}{\text{noise power within occupied bands}}$$

Output SNR per channel

$$\eta_{0,m} = \frac{\text{total output signal power}}{\text{total output noise power}}$$

Assumptions:

- $f_s = f_p$
- Sub-band bandwidths $B_j = \frac{2W}{2K_0+1} = \frac{2W}{K}$
- Sub-band central frequencies $f_{cj} = j \cdot \frac{f_p}{2}$
- Input noise is white with PSD N_0
- $\gamma_{m,k} \sim \mathcal{CN}(0, 1/\sqrt{K})$



$$\eta_I = \frac{\sum_{j \in \mathcal{K}_s} P_{S_j}}{N_0 2W/K} \quad \eta_{0,m} \leq \frac{\sum_{j \in \mathcal{K}_s} (|\gamma_{m,j}|^2 \cdot P_{S_j})}{\frac{N_0 2W}{K} \cdot \sum_k |\gamma_{m,k}|^2}$$

$$E\{\eta_{0,m}\} = \frac{1}{K} \eta_I, \text{ where } \frac{1}{K} \text{ is sampling rate reduction per channel}$$

Frequency-punctured mixing sequences

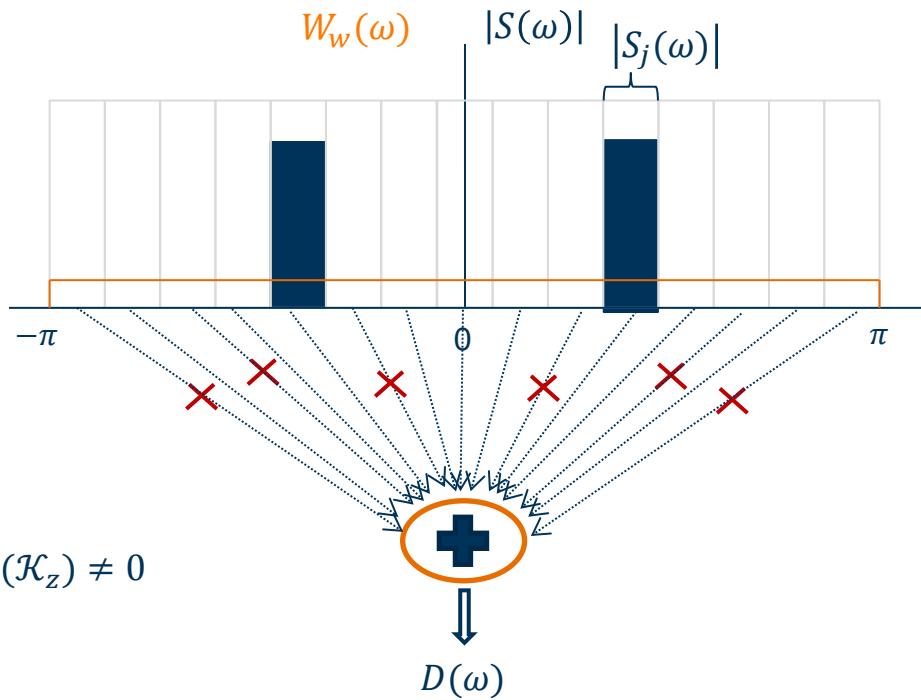
Let's build γ_m so that

$$D_m(\omega) = \sum_{k \in \mathcal{K}_m} \gamma_{m,k} \cdot S_k(\omega),$$

where $\mathcal{K}_m \subseteq \mathcal{K}: \{-K_0, \dots, 0, \dots, K_0\}$ defines the number $\hat{K} \leq K$ of subbands to take into account

$$\begin{aligned} \gamma_{m,k} &= 0, \text{ for } k \notin \mathcal{K}_m \text{ and} \\ \mathbb{E}\{\|\gamma_{m,k}\|\} &= \frac{1}{\sqrt{\hat{K}}}, \text{ for } k \in \mathcal{K}_m \end{aligned}$$

$$\begin{aligned} \mathbb{E}\{\eta_{0,m}\} &= \mathbb{E}\left\{\frac{\sum_{j \in \mathcal{K}_s \cap \mathcal{K}_m} (|\gamma_{m,j}|^2 \cdot P_{S_j})}{\frac{N_0 W}{K} \cdot \sum_{k \in \mathcal{K}_m} |\gamma_{m,k}|^2}\right\} \\ \mathbb{E}\{\eta_{0,m}\} &= \begin{cases} \frac{1}{\hat{K}} \cdot \eta_I, & \text{when } \mathcal{K}_s \subseteq \mathcal{K}_m \\ \frac{1}{\hat{K}} \cdot \beta \cdot \eta_I, & \text{when } \mathcal{K}_s \cap \mathcal{K}_m = \mathcal{K}_z, n(\mathcal{K}_z) \neq 0 \\ 0, & \mathcal{K}_s \cap \mathcal{K}_m = \emptyset \end{cases} \end{aligned}$$

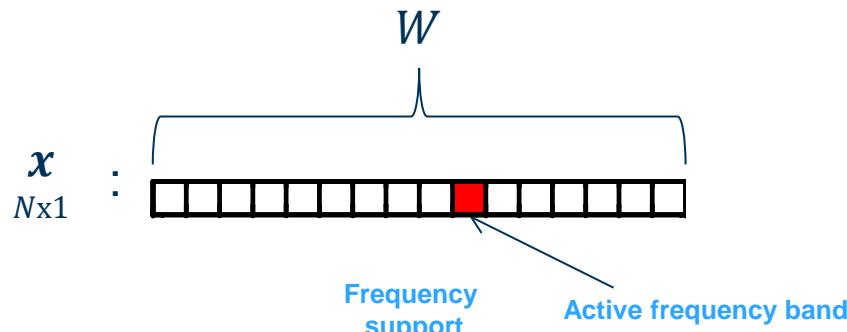


Simplified signal model

Simplified frequency domain signal model:

- $\boldsymbol{x} \in \mathbb{C}^N, \text{card}(\text{supp}\{|\boldsymbol{x}|\}) = L_s = 1, \|\boldsymbol{x}\|^2 = 1$
- $\boldsymbol{n} \in \mathbb{C}^N, n_k \sim \mathcal{CN}(0, N_0)$
- $\gamma_{m,k} \sim \mathcal{CN}(0,1), k = 1, \dots, N, \mathbb{E}\{\|\boldsymbol{\gamma}_m\|^2\} = 1$

$$\boldsymbol{d} = \boldsymbol{\Phi}^T \boldsymbol{r} = \boldsymbol{\Phi}^T (\boldsymbol{s} + \boldsymbol{w}) = \boldsymbol{B}(\boldsymbol{x} + \boldsymbol{n})$$



$$\boldsymbol{B} = \boldsymbol{\Phi}^T \boldsymbol{A} = \begin{bmatrix} \gamma_{1,1} & \cdots & \gamma_{1,N} \\ \vdots & \ddots & \vdots \\ \gamma_{m,1} & \cdots & \gamma_{m,N} \end{bmatrix} \begin{bmatrix} 1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 1 \end{bmatrix}$$

$$\begin{array}{c}
 \boldsymbol{d}_{M \times 1} \quad \boldsymbol{B}_{M \times N} \quad \boldsymbol{x}_{N \times 1} \quad \boldsymbol{B}_{M \times N} \quad \boldsymbol{n}_{N \times 1} \\
 \text{---} = \quad \text{---} + \quad \text{---} \quad \text{---} \quad \text{---}
 \end{array}$$

Introducing $K - \hat{K}$ zeros

$$\boldsymbol{B}_{M \times N}$$

so that $\forall k. \exists \gamma_{m,k}: \gamma_{m,k} \neq 0$

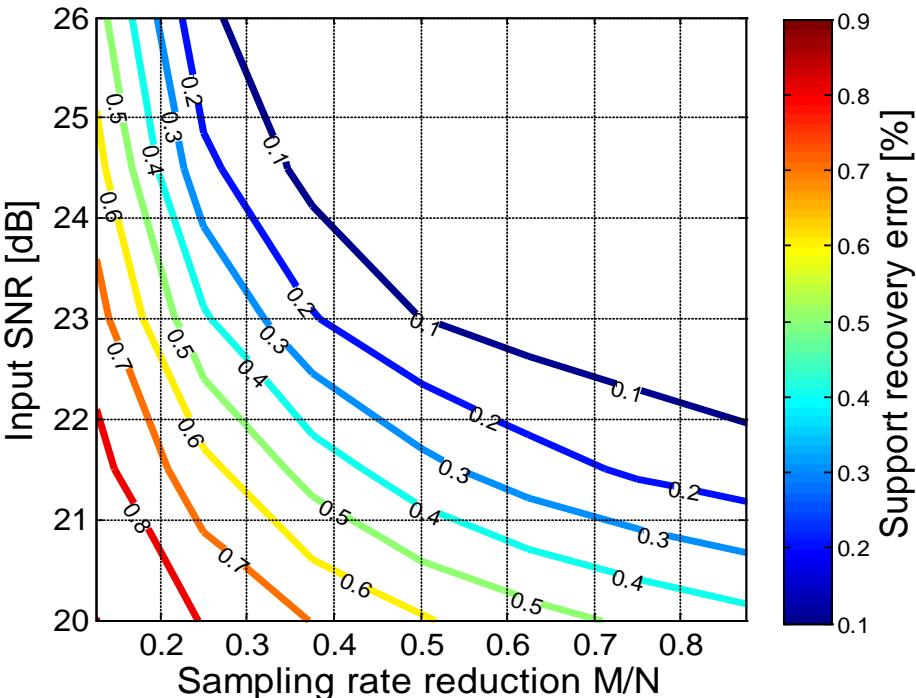
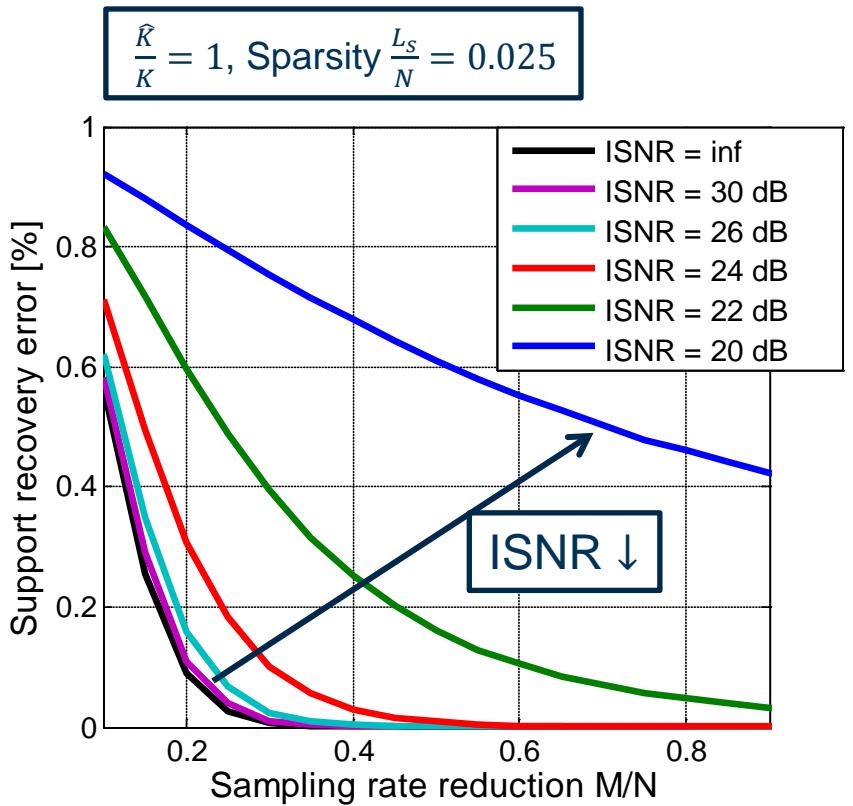
Numerical results.

Support recovery

Support recovery was based on the Basic Pursuit approach

$$\min_x \|x\|_1 \text{ subject to } \|d - Bx\|_2^2 \leq \varepsilon$$

$$\text{card}(x) = 1 \rightarrow \text{supp}(x) = \max(|d^T B|)$$



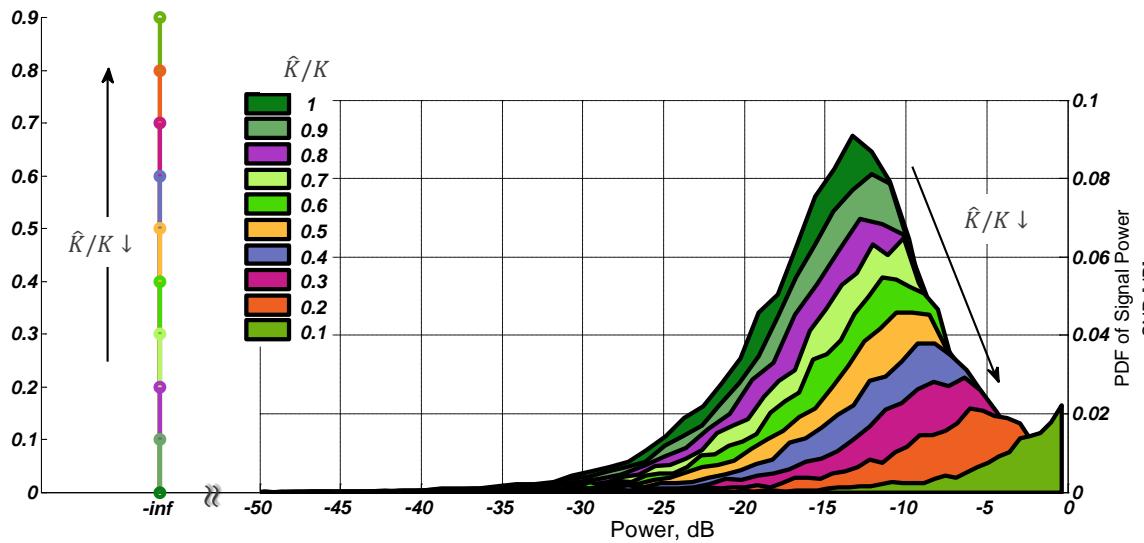
d $M \times 1$	B $M \times N$	x $N \times 1$
$=$		

Numerical results. Punctured γ_m SNR per channel

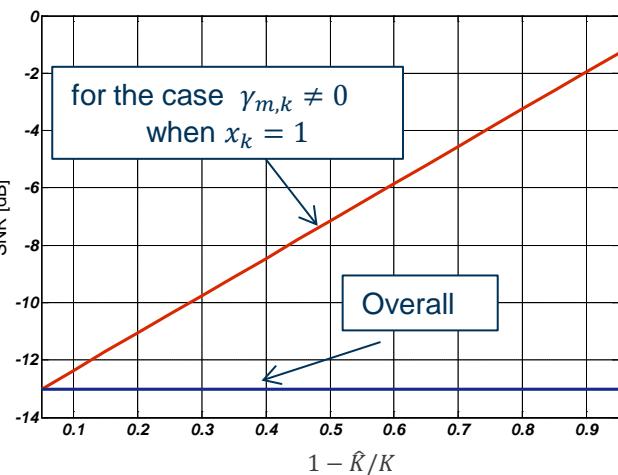
$$\eta_I = \frac{\|x\|^2}{E\{\|n_k\|^2\}} = \frac{1}{N_0}, \quad \eta_{O,m} = \frac{E\left\{\|\gamma_m^T x\|^2\right\}}{E\left\{\|\gamma_m^T n\|^2\right\}}$$

Input SNR $\eta_I = 20$ dB, $N = 20$

Probability density function of the output signal power

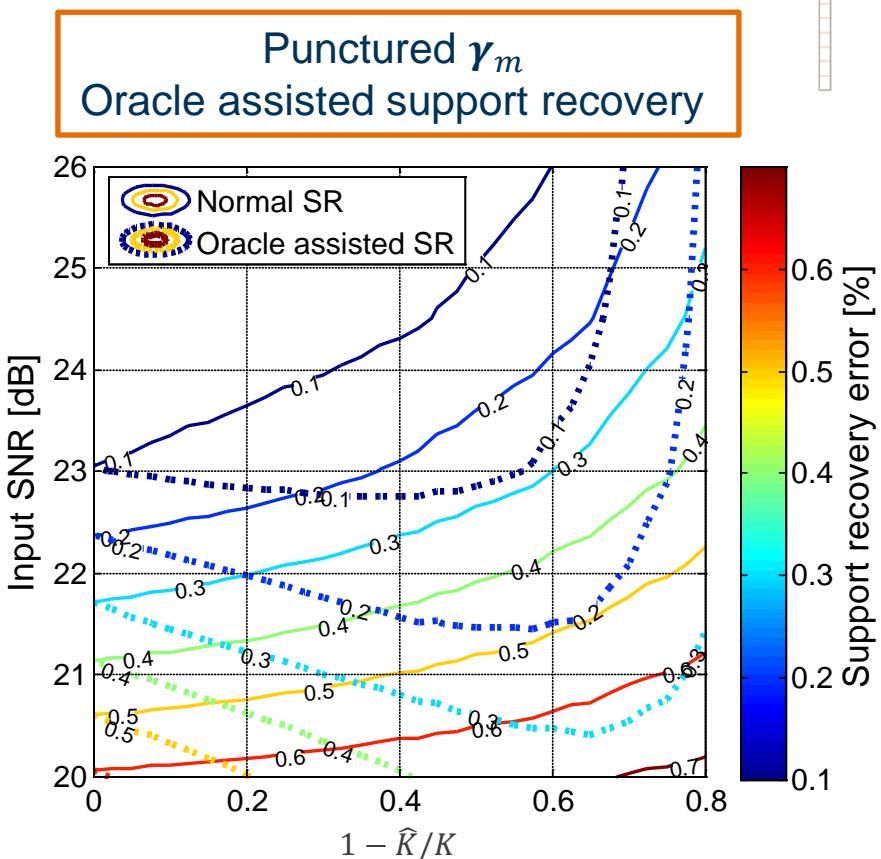
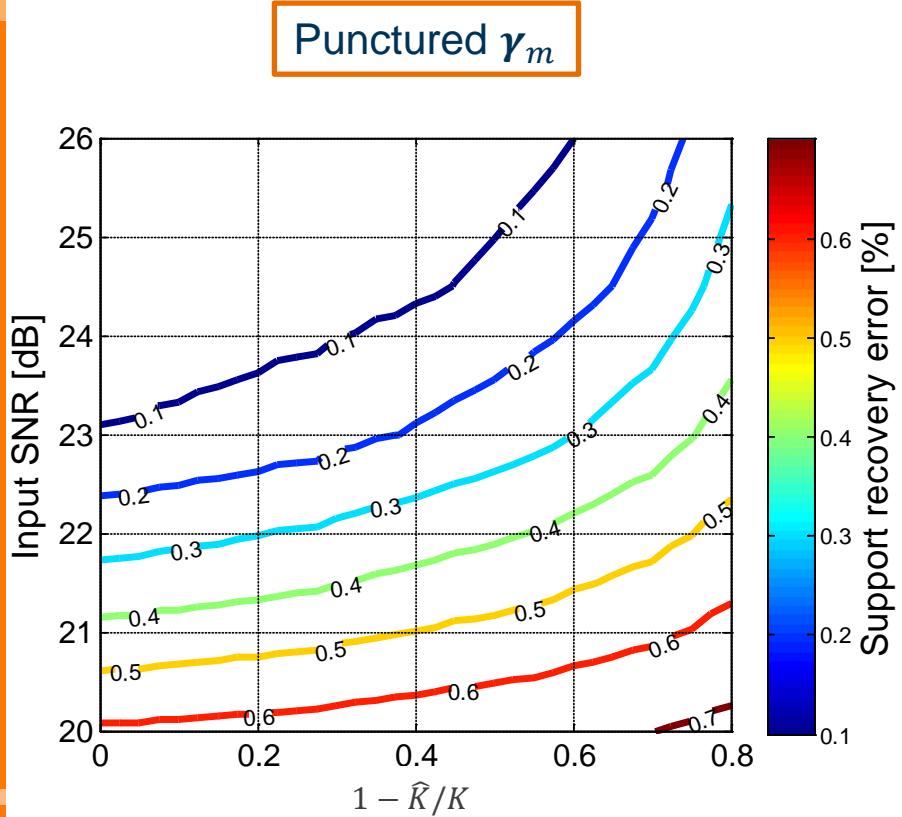


Expected output SNR



Numerical results. Punctured γ_m

Support recovery



Sampling rate reduction $\frac{M}{N} = 0.5$, Sparsity $\frac{L_s}{N} = 0.025$

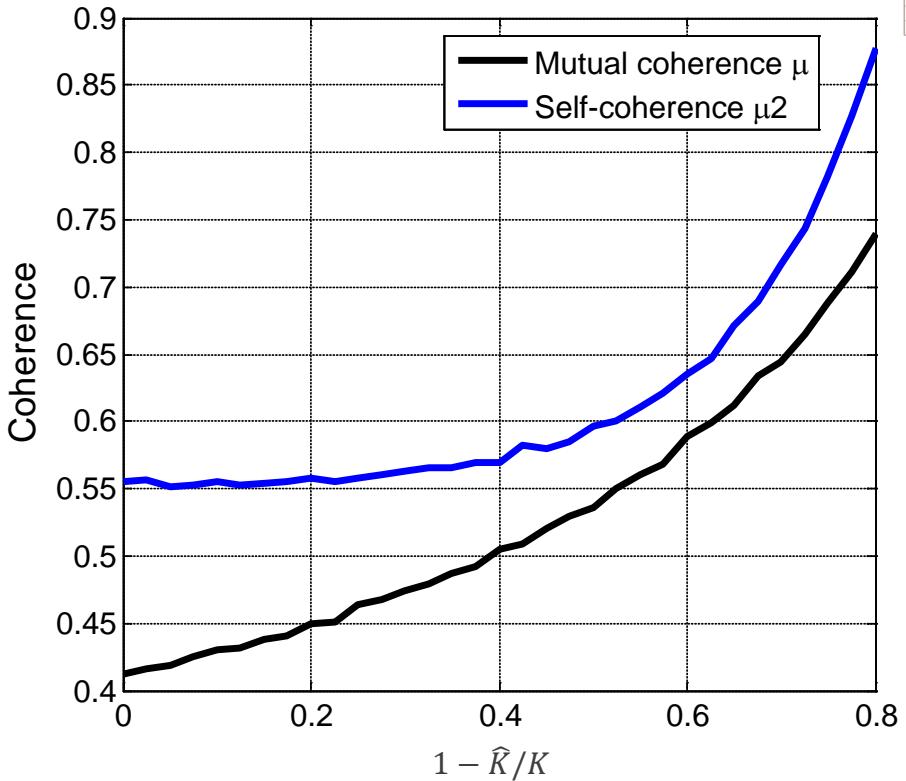
Numerical results. Punctured γ_m Support recovery and coherence

Mutual Coherence μ between Φ and A

$$\mu = \max_{i,j} \frac{|\langle \varphi_i, a_j \rangle|}{\|\varphi_i\| \|\alpha_j\|}$$

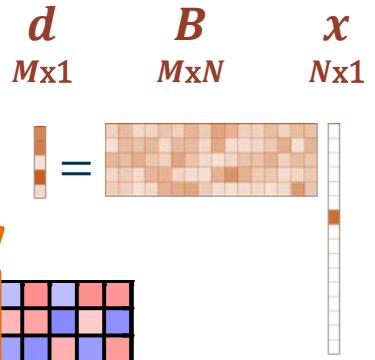
Self-Coherence μ_2 of matrix B

$$\mu_2 = \max_{\substack{i,j \\ i \neq j}} \frac{|\langle b_i, b_j \rangle|}{\|b_i\| \|b_j\|}$$



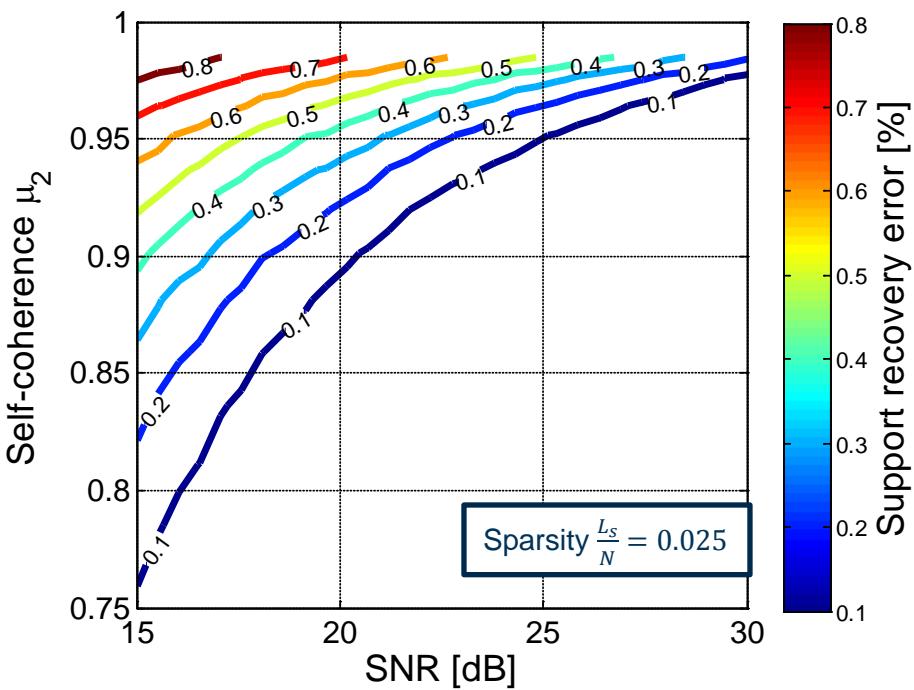
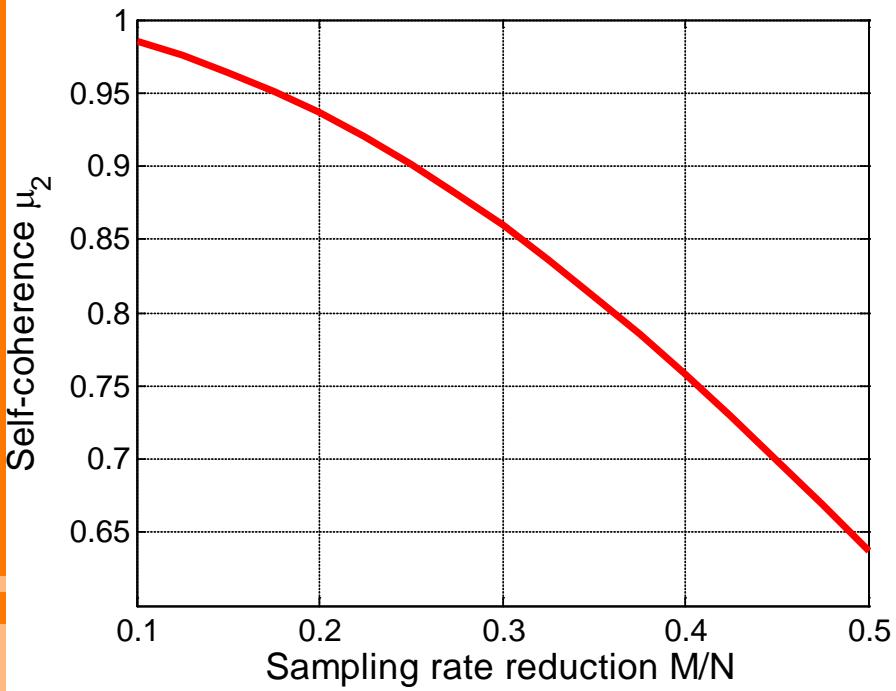
Sampling rate reduction $\frac{M}{N} = 0.5$, Sparsity $\frac{L_s}{N} = 0.025$

SNR and self-coherence



Self-coherence μ_2 of matrix B

$$\mu_2 = \max_{\substack{i,j \\ i \neq j}} \frac{|\langle b_i, b_j \rangle|}{\|b_i\| \|b_j\|}$$



d $M \times 1$	B $M \times N$	x $N \times 1$
$=$		

SNR and self-coherence

$$d^T B = (Bx)^T B + (Bn)^T B = x^T B^T B + n^T B^T B$$

Probability of error due to noise

Probability of confusing i^{th} row of B with j^{th}
 $P_E(i) = [|1 + \mathbf{n}^T \mathbf{B}^T \mathbf{b}_j| \leq |\beta_{ij} + \mathbf{n}^T \mathbf{B}^T \mathbf{b}_i|]$,

$$\text{where } \beta_{ij} = \mathbf{b}_j^T \mathbf{b}_i$$

If $\mathbf{n}^T \mathbf{B}^T$ white noise with variance σ^2

$$P_E(i) \approx Q\left(-\sqrt{\frac{1-\beta_{ij}}{2\sigma^2}}\right) \cdot Q\left(\frac{\beta_{ij}}{\sqrt{\sigma^2}}\right) + Q\left(-\sqrt{\frac{1+\beta_{ij}}{2\sigma^2}}\right) \cdot Q\left(-\frac{\beta_{ij}}{\sqrt{\sigma^2}}\right)$$

Total probability of mistake

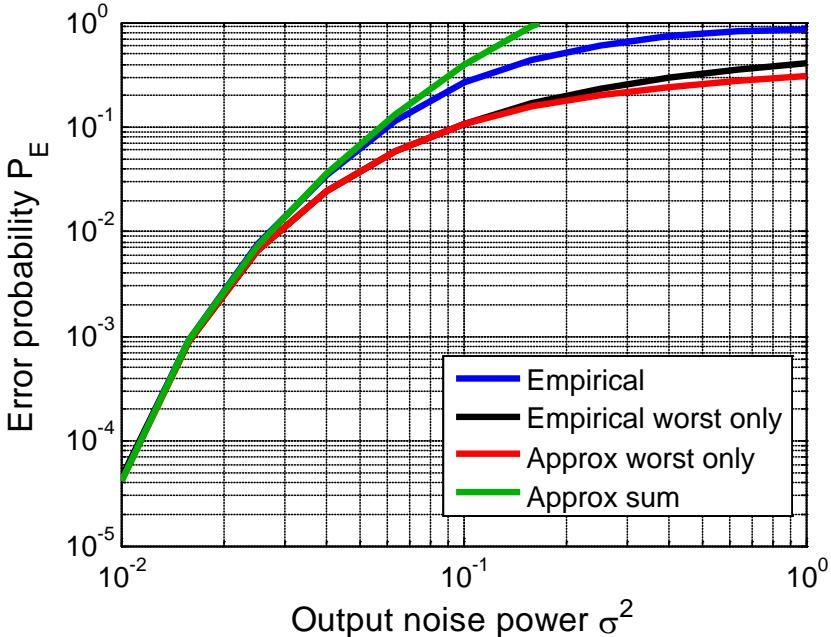
$$P_E = [|1 + \mathbf{n}^T \mathbf{B}^T \mathbf{b}_j| \leq \max_i |\beta_{ij} + \mathbf{n}^T \mathbf{B}^T \mathbf{b}_i|]$$

Upper bound

$$P_E \leq \sum_i P_E(i)$$

Lower bound

$$P_E(i_{\text{worst}}) \leq P_E$$



Conclusions

- The effect of noise folding significantly degrades recovery performance.
- Noise mitigation capabilities via measurement kernel manipulations are limited by the coherence properties of the resulting kernel.
- The influence of the noise added to the signal prior measurement on the support recovery has been studied numerically revealing the relation between input SNR, number of channels, mutual and self-coherence.

Thank you for your attention!

Anastasia Lavrenko

Electronic Measurement lab

International Graduate School on Mobile Communications

TU Ilmenau, Germany

anastasia.lavrenko@tu-ilmenau.de

